英

平成 30 年度 秋季募集
(平成 31 年 4 月入学)
東北大学大学院機械系 4 専攻入学試験

試験問題冊子

数学A　MATHEMATICS A

平成 30 年 8 月 28 日(火)
Tuesday, August 28, 2018　　9:30 － 11:00

Notice

1. Do not open this test booklet until instructed to do so.

2. A test booklet, answer sheets, draft sheets, and a selected-problems form are provided. Put your examinee number on each of the answer sheets, the draft sheets, and the form.

3. Select three of the four problems and answer them. Indicate your selection on the selected-problems form. Use two answer sheets for each problem.

4. At the end of the examination, double-check your examinee number and the problem numbers on the answer sheets. Put your answer sheets in numerical order on top of the other sheets, place them beside the test booklet, and wait for collection by an examiner. Do not leave your seat before instructed to do so by the examiner.

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数学 A　MATHEMATICS A

1. Solve the following problems, where a is a positive constant.

(1) Evaluate the area of the region D_1 in the xy plane defined by

$$D_1 = \{ (x, y) \mid r \leq a(1 + \cos\theta) \},$$

where r and θ are the polar coordinates with $x = r\cos\theta$ and $y = r\sin\theta$.

(2) Evaluate the area of the region D_2 in the xy plane defined by

$$D_2 = \left\{ (x, y) \mid \frac{x^2}{2a} \leq y \leq \frac{a^3}{x^2 + a^2} \right\}.$$

(3) Evaluate the length of the curve C in the xy plane defined by

$$C = \{ (x, y) \mid 3ay^2 = x(x - a)^2, \quad x \leq a \}.$$

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2. Find the general solutions of the following ordinary differential equations.

(1) $(x+1)\dfrac{dy}{dx} - 3y - (x+1)^3 = 0$

(2) $\dfrac{d^2y}{dx^2} - 2\dfrac{dy}{dx} + 5y = e^x \cos x$

(3) $x\dfrac{dy}{dx}\cos\dfrac{y}{x} + x = y\cos\dfrac{y}{x}$

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3. Consider the 3×3 matrix A which satisfies

$$\begin{pmatrix} 2x & y+1 & z+6 \\ x & 2y & 3 \\ x & 2 & 2z+3 \end{pmatrix} = A \begin{pmatrix} x & 0 & 3 \\ 0 & y & 0 \\ 0 & 1 & z \end{pmatrix}$$

for any real numbers x, y, and z. Solve the following problems.

(1) Let $\boldsymbol{a}_1, \boldsymbol{a}_2$, and $\boldsymbol{a}_3$ be column vectors such that $A = (\boldsymbol{a}_1, \boldsymbol{a}_2, \boldsymbol{a}_3)$. Find $\boldsymbol{a}_1, \boldsymbol{a}_2$, and $\boldsymbol{a}_3$.

(2) Find the eigenvalues and the eigenvectors of A.

(3) Find the inverse matrix of A.

(4) Find the general form of the 3×3 matrix X that satisfies $A^n X = X A^n$ for any positive integer n.

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数学 A　MATHEMATICS A

4. In the Cartesian coordinate system (x, y, z), the vector field $\boldsymbol{A}$ is given by

$$\boldsymbol{A} = y\boldsymbol{i} + z\boldsymbol{j} + x\boldsymbol{k},$$

where $\boldsymbol{i}$, $\boldsymbol{j}$, and $\boldsymbol{k}$ are the fundamental vectors in the x, y, and z directions, respectively. In addition, the curve C is given by

$$\boldsymbol{r} = (\cos t)\,\boldsymbol{i} + (\sin t)\,\boldsymbol{j} + t\boldsymbol{k} \qquad (0 \leq t \leq 2\pi),$$

as shown in Fig. 1 on the next page. Solve the following problems.

(1) Obtain $\nabla \cdot \boldsymbol{A}$ and $\nabla \times \boldsymbol{A}$.

(2) Let L be the line connecting the two endpoints of C as shown in Fig. 1 on the next page. Evaluate the integral

$$\int_L \boldsymbol{A} \cdot d\boldsymbol{r},$$

where L is oriented such that z increases.

(3) Let S be the surface generated by moving the line connecting C with the z axis at the same z coordinate in the range $0 \leq z \leq 2\pi$. Then S is given by

$$\boldsymbol{r} = (r\cos\theta)\,\boldsymbol{i} + (r\sin\theta)\,\boldsymbol{j} + \theta\boldsymbol{k} \qquad (0 \leq r \leq 1,\ \ 0 \leq \theta \leq 2\pi).$$

Evaluate the integral

$$\int_S (\nabla \times \boldsymbol{A}) \cdot \boldsymbol{n} dS,$$

where $\boldsymbol{n}$ is the unit normal vector of S with a non-negative z component.

(4) Evaluate the integral

$$\int_C \boldsymbol{A} \cdot d\boldsymbol{r},$$

where C is oriented such that z increases.

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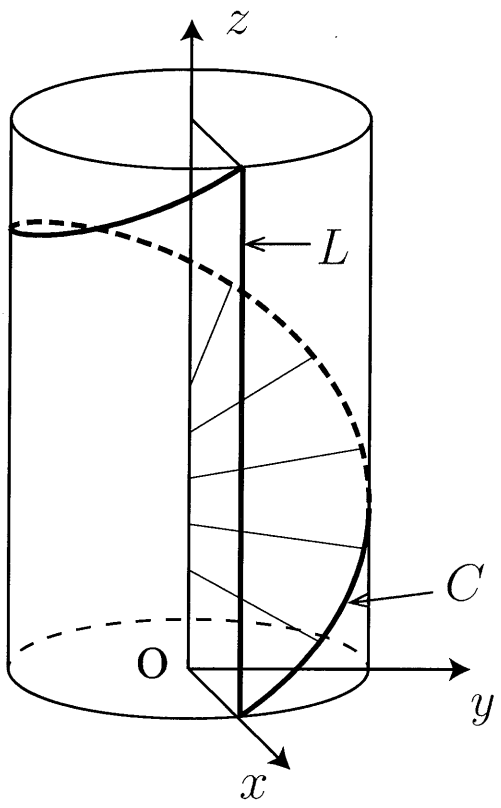

Fig. 1

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(平成 31 年 4 月入学)
東北大学大学院機械系 4 専攻入学試験

試験問題冊子

数学B　MATHEMATICS B

平成 30 年 8 月 28 日(火)
Tuesday, August 28, 2018　13:30 － 15:00

Notice

1. Do not open this test booklet until instructed to do so.

2. A test booklet, answer sheets, draft sheets, and a selected-problems form are provided. Put your examinee number on each of the answer sheets, the draft sheets, and the form.

3. Select two of the three problems, and answer them. Indicate your selection on the selected-problems form. Use two answer sheets for each problem.

4. At the end of the examination, double-check your examinee number and the problem numbers on the answer sheets. Put your answer sheets in numerical order on top of the other sheets, place them beside the test booklet, and wait for collection by an examiner. Do not leave your seat before instructed to do so by the examiner.

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数学 B　MATHEMATICS B

1. The Fourier transform $F(\omega)$ of a function $f(t)$ and its inverse transform are defined by

$$F(\omega) = \int_{-\infty}^{\infty} f(t)\, e^{-i\omega t}\, dt\,,$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega)\, e^{i\omega t}\, d\omega\,.$$

Solve the following problems.

(1) Obtain the Fourier transform of the function $g(t)$ given by

$$g(t) = \begin{cases} 1 & (|t| \leq 1) \\ 0 & (|t| > 1)\,. \end{cases}$$

(2) $X(\omega)$ and $Y(\omega)$ are the Fourier transforms of functions $x(t)$ and $y(t)$, respectively, and satisfy the following relation

$$Y(\omega) = -\frac{1}{\pi} \int_{-\infty}^{\infty} X(\omega') \frac{1}{\omega - \omega'}\, d\omega'\,.$$

Find the relation between $x(t)$ and $y(t)$, using that the Fourier transform of the following function

$$h(t) = \begin{cases} -1 & (t < 0) \\ 1 & (t \geq 0) \end{cases}$$

is given by $H(\omega) = \dfrac{2}{i\omega}$.

(3) Obtain $X(\omega)$ which satisfies the following relation

$$\frac{\sin\omega}{\omega} = -\frac{1}{\pi} \int_{-\infty}^{\infty} X(\omega') \frac{1}{\omega - \omega'}\, d\omega'\,.$$

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数学 B　MATHEMATICS B

2. The Laplace transform of a function $f(t)$ is defined by

$$\mathcal{L}[f(t)] = F(s) = \int_0^\infty f(t)\, e^{-st}\, dt\,.$$

When a is a positive constant, solve the following problems.

(1) Obtain the inverse Laplace transform of $e^{-as} F(s)$.

(2) Obtain the Laplace transform $G(s)$ of the function $g(t)$ with period $2a$ defined by

$$g(t) = \begin{cases} 1 & (0 \leq t < a) \\ -1 & (a \leq t < 2a)\,. \end{cases}$$

(3) Obtain the inverse Laplace transform of $\dfrac{1}{s} G(s)$ and draw the graph for $0 \leq t \leq 4a$, where $G(s)$ is obtained in problem (2).

(4) Obtain the inverse Laplace transform of $\dfrac{2e^{-as}}{s^2\,(1 + e^{-as})}$ for $0 \leq t \leq 4a$ and draw the graph.

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3. The function $u(x,t)$ satisfies the partial differential equation

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2} \qquad (0 < x < L, \quad t > 0)$$

with the boundary conditions

$$u(0,t) = 0, \quad \frac{\partial u(L,t)}{\partial x} = 0, \quad \text{and} \quad u(x,0) = f(x),$$

where α and L are positive constants. Solve the following problems.

(1) Find the general solution $u(x,t)$.

(2) Find $u(x,t)$ when $f(x) = x(3L^2 - x^2)$.

(3) For $u(x,t)$ of problem (2), draw the schematic graph of $y = u(x,t)$ at $t = 0$, $t = t_1$, and $t = \infty$ in the xy plane, where $0 < t_1 < \infty$.

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平成 30 年度 秋季募集
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東北大学大学院機械系 4 専攻入学試験

試験問題冊子
【専門科目　Specialized Subjects】

熱力学	THERMODYNAMICS	P1~P2
流体力学	FLUID DYNAMICS	P3~P4
材料力学	STRENGTH OF MATERIALS	P5~P6
機械力学	DYNAMICS OF MECHANICAL SYSTEMS	P7~P8
制御工学	CONTROL ENGINEERING	P9~P10

平成 30 年 8 月 29 日 (水)　9:00 － 12:00
Wednesday, August 29, 2018　9:00 － 12:00

Notice

1. Do not open this test booklet until instructed to do so.
2. A test booklet, answer sheets, draft sheets, and two selected-subjects forms are provided. Put your examinee number on each of the answer sheets, the draft sheets, and the form.
3. Select two subjects from the five subjects in the booklet and answer all problems in each subject. Indicate your selection on the selected-subjects form. Use one set of two answer sheets for each subject, and use one sheet per problem.
4. At the end of the examination, double-check your examinee number and the problem numbers on the answer sheets. Put your answer sheets in numerical order on top of the other sheets, place them beside the test booklet, and wait for collection by an examiner. Do not leave your seat before instructed to do so by the examiner.

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熱 力 学　THERMODYNAMICS

1. Answer the following questions regarding quasi-static compression processes of an ideal gas in a closed system that consists of a cylinder and a piston. Pressure and specific volume of the initial state 1 of the processes are p_1 and v_1, respectively. The specific heat ratio and gas constant of the ideal gas are κ and R, respectively.

   (1) When the gas is compressed isothermally from the state 1 to the final state 2, indicate the relation among the pressures and specific volumes at the state 1 and the state 2. Pressure and specific volume of the final state 2 are p_2 and v_2, respectively.

   (2) Obtain the change of specific entropy during the isothermal compression process of question (1).

   (3) Obtain the work received by the gas during an adiabatic compression process from the state 1. Pressure at the final state 3 of the process is p_3.

   (4) When the same amount of the work is conducted during the isothermal compression process of question (1) and during the adiabatic compression process of question (3), describe which one of the final specific volumes of the isothermal compression process v_2 and of the adiabatic compression process v_3 is larger with its reason. Express the pressure ratio p_3/p_2 by the specific heat ratio of the gas κ, the initial temperature of the system T_1 and the final temperature of the adiabatic compression process T_3.

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2. Answer the following questions regarding the general thermodynamic relation.

(1) Express the equation of dh which is the differential change of specific enthalpy h using necessary symbols from pressure p, specific entropy s, temperature T, specific volume v and their differential changes dp, ds, dT and dv.

(2) Derive the following equation, where c_p is specific heat at constant pressure.

$$ds = \left(\frac{\partial s}{\partial p}\right)_T dp + \frac{c_p}{T} dT$$

(3) Derive the following Maxwell thermodynamic relation using the equation of specific Gibbs free energy $g = h - Ts$.

$$\left(\frac{\partial v}{\partial T}\right)_p = -\left(\frac{\partial s}{\partial p}\right)_T$$

(4) Derive the following equation using the relations in questions (1), (2) and (3).

$$dh = c_p dT + \left\{ v - T\left(\frac{\partial v}{\partial T}\right)_p \right\} dp$$

(5) Show that specific heat at constant pressure of an ideal gas is independent of pressure using the equation shown in question (4).

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流 体 力 学　FLUID DYNAMICS

1. Consider a two-dimensional steady flow of an incompressible viscous fluid induced between two flat plates, which are placed horizontally. The upper plate is stationary, whereas the lower one is sliding horizontally at constant speed U. The x axis is taken in the direction of the movement of the lower plate, and the y axis is taken upward and perpendicularly to the plates, so that the surface of the lower plate is at $y = 0$. It is assumed that the fluid velocity is parallel to the x axis everywhere and the pressure p does not vary in the y direction. The viscosity of the fluid is constant at μ. In this case, the Navier-Stokes equation reduces to

$$\frac{dp}{dx} = \mu \frac{d^2u}{dy^2}.$$

Here, u is the x component of the fluid velocity and a function of y alone. Answer the following questions.

(1) Consider the case when the two plates are sufficiently large and distance h apart, as shown in Fig. 1.

a) Derive the following expression for u:

$$u = -\frac{1}{2\mu}\frac{dp}{dx}(h-y)y + \frac{U}{h}(h-y).$$

b) Derive the following expression for the volume flow rate Q, per unit width of the plates, across a cross-section normal to the x axis:

$$Q = -\frac{h^3}{12\mu}\frac{dp}{dx} + \frac{1}{2}Uh.$$

(2) Consider the case when the length of the upper plate is L and a step exists at its center, as shown in Fig. 2. The left edge of the upper plate is placed at $x = 0$. The distances between the upper and lower plates are constant at H and $H/2$ in the regions of $0 \le x < L/2$ and $L/2 \le x \le L$, respectively. For simplicity, the expressions for the fluid velocity u and the volume flow rate Q given in question (1) are assumed to be applicable to each of the regions including a neighborhood of the step. Here, the pressures at $x = 0$ and $x = L$ are p_a.

a) Express the volume flow rate Q using U and H. Note that the pressure p is continuous at $x = L/2$.

b) Express the y component of the force F_y, per unit width of the upper plate, exerted by the fluid pressure on the bottom surface of that plate using L, U, H, μ and p_a.

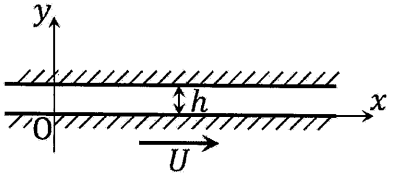

Fig. 1

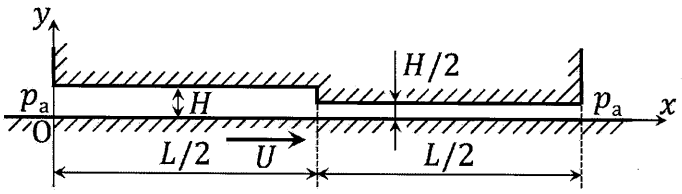

Fig. 2

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2. Consider a two-dimensional steady potential flow of an inviscid incompressible fluid. Answer the following questions.

(1) The flow around a vortex filament located at the origin is given by the following complex velocity potential,

$$W(z) = i\,k \ln z \ ,$$

where k is a positive real number, i is the imaginary unit, ln is the natural logarithm, z is a complex variable which is expressed by $z = re^{i\theta}$, and r and θ are radial and circumferential coordinates, respectively.

a) Obtain the velocity potential $\Phi(r, \theta)$ and the stream function $\Psi(r, \theta)$.

b) Obtain the counterclockwise circulation Γ along the circle of radius r centered at the origin.

c) Answer whether the circulating flow around the vortex filament is a free vortex or a forced vortex.

(2) As shown in Fig. 3, three vortex filaments A, B and C with circulation Γ_A, Γ_B and Γ_C, respectively, are aligned at regular intervals of h. Assuming an infinite domain of fluid where the fluid velocity approaches to zero at infinity, a vortex filament moves with the velocity induced by the other vortex filaments. Obtain the relationship among Γ_A, Γ_B and Γ_C in the case when all the vortex filaments stand still in the flow field. Here, Γ_A is assumed to be nonzero.

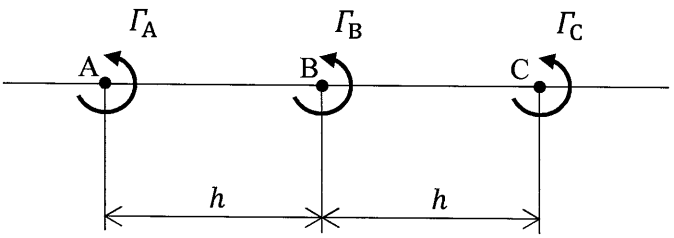

Fig. 3

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材 料 力 学　STRENGTH OF MATERIALS

1. As shown in Fig. 1, a two-dimensional truss composed of four uniform bars AF, BF, CF, and DF is pin-connected at their ends on a horizontal rigid ceiling and point F. The distance from point F to the rigid ceiling is h. The angle of the bars BF and CF from the vertical direction is θ_1 and that of AF and DF is θ_2. Assume $0 < \theta_1 < \theta_2 < \pi/2$. Young's modulus and the cross-sectional area of the four bars are E and S, respectively. A vertical downward load P is applied at point F. Neglect the weight of the bars. Answer the following questions.

   (1) Denote the axial forces in AF, BF, CF, and DF by R_{AF}, R_{BF}, R_{CF}, and R_{DF}, respectively. Derive the equations of force equilibrium in both horizontal and vertical directions for the truss.
   (2) Show the axial strain of each bar ε_{AF}, ε_{BF}, ε_{CF}, and ε_{DF} in terms of R_{AF}, R_{BF}, R_{CF}, and R_{DF}.
   (3) Indicate the relationship between the elongation of each bar Δl_{AF}, Δl_{BF}, Δl_{CF}, and Δl_{DF}, and the vertical displacement δ at point F.
   (4) Determine the axial forces R_{AF}, R_{BF}, R_{CF}, and R_{DF}.
   (5) Find the vertical displacement δ at point F.

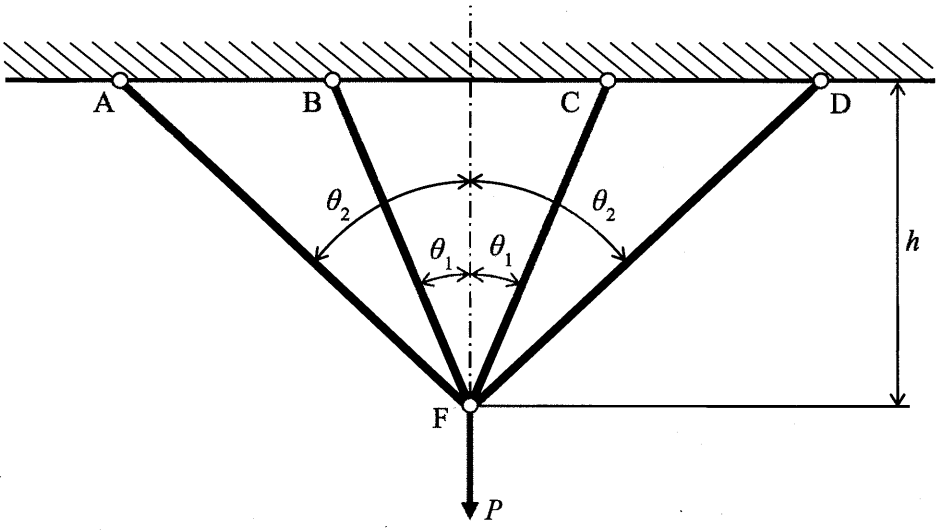

Fig. 1

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2. Consider an L-shaped frame ABC which consists of beams AB and BC. The frame is fixed at point A. The length of the beams AB and BC is $2L$, and flexural rigidity EI of the beams is constant. Neglect both the weight of the beams and the elongation of the neutral axis of the beams. Answer the following questions.

(1) A bending moment M_B is applied at point B, as shown in Fig. 2(a). Determine the deflection angle at point B.
(2) A load W is applied at the middle point D of BC vertically in the downward direction, as shown in Fig. 2(b). Determine the deflection of the frame at right end C.
(3) The L-shaped frame ABC is simply supported at right end C, as shown in Fig. 2(c). Determine the reaction at right end C, when a load W is applied at point D vertically in the downward direction.

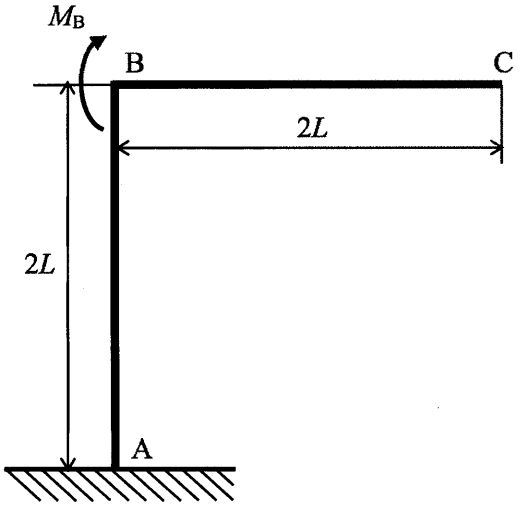

Fig. 2(a)

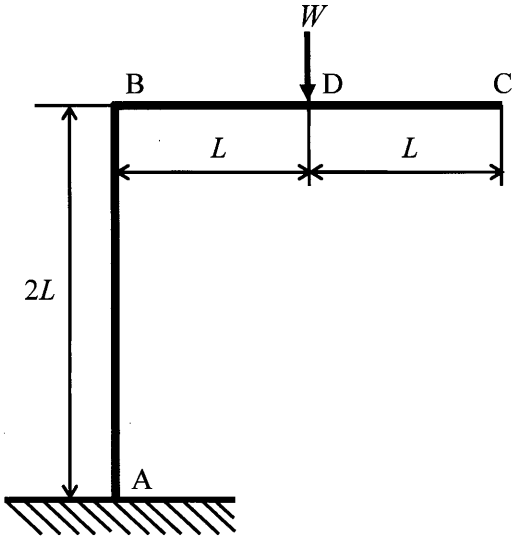

Fig. 2(b)

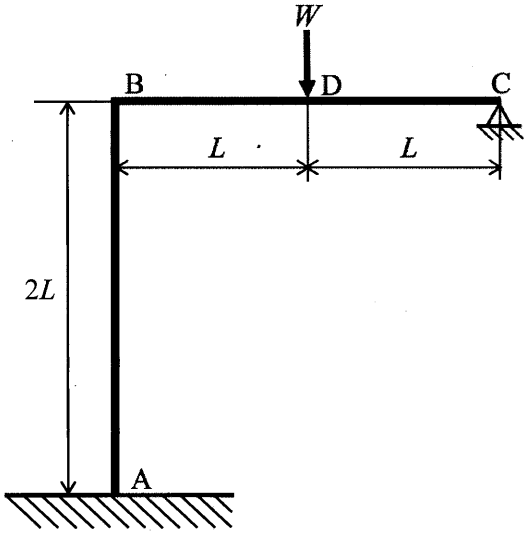

Fig. 2(c)

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機械力学 DYNAMICS OF MECHANICAL SYSTEMS

1. Consider a system consisting of a mass m, two springs with spring constants k_1 and k_2, a dashpot with damping coefficient c, and a beam with length L, Young's modulus E and moment of inertia of area I, as shown in Fig. 1. Assume that the masses of the springs, the dashpot and the beam are negligible, and that the mass m vibrates only in the horizontal direction with a sufficiently small displacement. The displacement of the mass m from the equilibrium position is denoted by $x(t)$, where t is time. Answer the following questions.

(1) Express the equivalent spring constant k_3 of the beam by using L, E and I.

(2) Find the equivalent spring constant K of the system.

(3) Obtain the critical damping coefficient of the system.

(4) Find the damped natural period T of the system, when the system is underdamped.

(5) Obtain the ratio of $x(t)$ at two different times separated by the period T under the condition of question (4) when $x(t) \neq 0$.

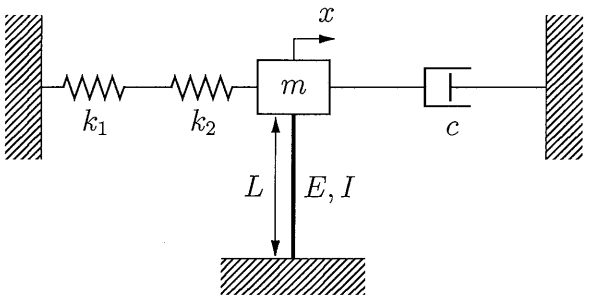

Fig. 1

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2. Consider a system consisting of a uniform rotating disk with mass m_1, radius r and moment of inertia J, two springs with spring constants k_1 and k_2, and a trailer with mass m_2, as shown in Fig. 2. The right end of the spring with spring constant k_1 is connected to the center axis O of the disk through a frictionless bearing, and the left end is fixed to the trailer. The right end of the spring with spring constant k_2 is connected to the trailer, and the left end is fixed to the wall. The disk rotates on the trailer without slipping and the trailer vibrates only in the horizontal direction. The angular displacement of the disk and the displacement of the trailer from the equilibrium positions are denoted by θ and x, respectively. Assumimg that the masses of the springs are negligible, answer the following questions.

(1) Obtain the kinetic energy T of the system.

(2) Obtain the potential energy U of the system.

(3) Derive the equations of motion of the system.

(4) When $m_1 = 2m$, $m_2 = m$, and $k_1 = k_2 = k$, find the natural angular frequencies of the system using $J = mr^2$.

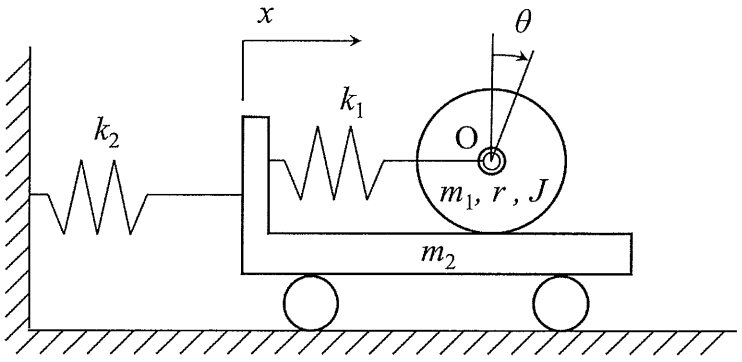

Fig. 2

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制御工学 CONTROL ENGINEERING

1. Solve the following problems. s is the Laplace operator and t is time.

(1) Derive the unit step response of the system shown in Fig. 1 and draw its outline.

(2) Obtain the transfer function $G(s)$ from $U(s)$ to $Y(s)$ of the system shown in Fig. 1. Obtain also the poles and zeros of the transfer function.

(3) Consider a feedback control system shown in Fig. 2. The transfer function of the controlled system $P(s)$ is given by

$$P(s) = \frac{4}{(s+1)(s+4)}.$$

When a unit ramp function $r(t) = t$ is applied as a reference input, the system has a steady-state velocity error e_v $(0 < e_v < \infty)$. In this case, select a controller $C(s)$ from (i) – (iii) and explain the reason. Note K_1, K_2, and K_3 are positive constants.

(i) $C(s) = K_1$, (ii) $C(s) = \dfrac{K_1 s + K_2}{s}$, (iii) $C(s) = \dfrac{K_1 s^2 + K_2 s + K_3}{s^2}$.

(4) Consider the feedback control system in problem (3). Find the conditions so that the system is stable. Find also the conditions so that the steady-state velocity error e_v of the system satisfies $e_v \leq 0.1$.

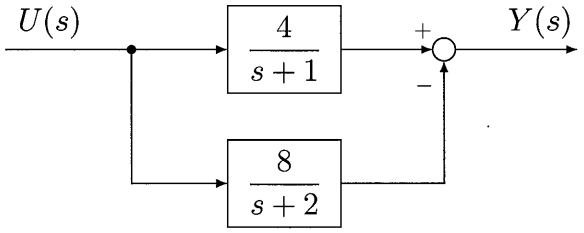

Fig. 1

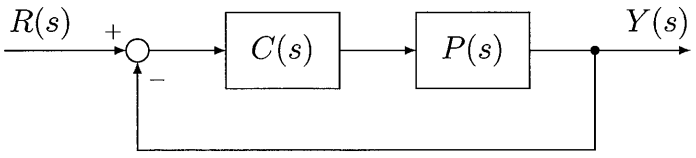

Fig. 2

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2. Consider the following controllable linear time-invariant system

$$\frac{d\boldsymbol{x}}{dt} = \boldsymbol{A}\boldsymbol{x} + \boldsymbol{B}\boldsymbol{u},$$
$$\boldsymbol{y} = \boldsymbol{C}\boldsymbol{x},$$

where $\boldsymbol{x}$ is a state vector, $\boldsymbol{u}$ is input, and $\boldsymbol{y}$ is output.

It is known that the optimal control input to minimize a criterion function

$$J = \frac{1}{2}\int_0^\infty (\boldsymbol{x}^T\boldsymbol{Q}\boldsymbol{x} + \boldsymbol{u}^T\boldsymbol{R}\boldsymbol{u})dt$$

is given by $\boldsymbol{u} = -\boldsymbol{R}^{-1}\boldsymbol{B}^T\boldsymbol{P}\boldsymbol{x}$, where $\boldsymbol{P}$ is the positive definite solution of the following Ricatti equation,

$$\boldsymbol{P}\boldsymbol{A} + \boldsymbol{A}^T\boldsymbol{P} - \boldsymbol{P}\boldsymbol{B}\boldsymbol{R}^{-1}\boldsymbol{B}^T\boldsymbol{P} + \boldsymbol{Q} = \boldsymbol{O},$$

where $\boldsymbol{Q}$ and $\boldsymbol{R}$ denote the weight matrices, and $\boldsymbol{O}$ denotes the zero matrix. Solve the following problems.

(1) Consider the electric circuit shown in Fig. 3 in which the inductance, the resistance, and the capacitance are given by l, r, and c, respectively. The input and output voltages of the circuit are given by e_i and e_o, respectively. Let i be the current flowing through the coil and v be the voltage applied to the capacitor. Derive the state equation and the output equation of the system in which the state vector, the input, and the output are defined as $\boldsymbol{x} = (i, v)^T$, $u = e_i$, and $y = e_o$, respectively.

(2) Obtain the matrix $\boldsymbol{P} = \begin{pmatrix} p_1 & p_2 \\ p_2 & p_3 \end{pmatrix}$ and the optimal control input u, where the circuit constants are given as $l = r = c = 1$, and the weights are given as $R = 1$ and $\boldsymbol{Q} = \begin{pmatrix} 6 & 0 \\ 0 & 3 \end{pmatrix}$ in problem (1).

(3) Explain how the initial value response of the system is influenced, when $\boldsymbol{Q}$ is not changed while R is increased in problem (2).

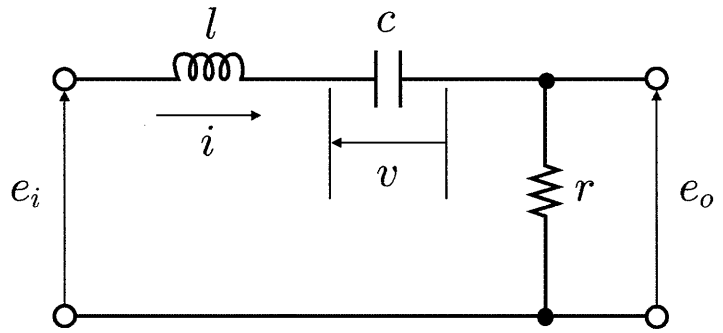

Fig. 3

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